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THE DENJOY-WOLFF ITERATION PROPERTY IN THE HILBERT BALL

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Dedicated to Professor Sompong Dhompongsa on his 65th birthday

ABSTRACT. We first present new conditions which are equivalent to the Denjoy-Wolff iteration property in the Hilbert ball and then use them to find new classes of mappings with this property.

1. INTRODUCTION

Let B_H denote the Hilbert ball, that is, the open unit ball of a complex Hilbert space H, and let k_{B_H} denote the Kobayashi distance in B_H . This paper concerns the asymptotic behavior of the iterates of holomorphic self-mappings and, more generally, of k_{B_H} -nonexpansive self-mappings of the Hilbert ball B_H in the spirit of the celebrated Denjoy-Wolff theorem, which we now recall.

Theorem 1.1 ([15, 58, 59]; see also [11, 55, 60] and [57]). Let Δ be the open unit disc in the complex plane \mathbb{C} . If a holomorphic function $F : \Delta \to \Delta$ does not have a fixed point, then there is a unique point ξ on the boundary $\partial \Delta$ of Δ such that the sequence of iterates $\{F^n\}$ of F converges pointwise to ξ , uniformly on compact subsets of Δ .

The most general result of this type in the case of \mathbb{C}^k is due to the first author [6]. Before stating it, we recall that a bounded and convex domain D in a complex Banach space $(X, \|\cdot\|)$ is said to be *strictly convex* if for each $x, y \in \overline{D}$, the open segment

$$(x, y) = \{z \in X : z = sx + (1 - s)y \text{ for some } 0 < s < 1\}$$

lies in D ([16]).

Theorem 1.2 ([6]; see also [7,10] and [3]). If D is a bounded and strictly convex domain in \mathbb{C}^k and $F : D \to D$ is holomorphic and fixed point free, then there exists a point $\xi \in \partial D$ such that the sequence $\{F^n\}$ of iterates of F converges in the compact-open topology to the constant mapping taking the value ξ .

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But in the case of an *infinite dimensional* complex Hilbert space, the situation changes radically, that is, the Denjoy-Wolff theorem no longer holds. More precisely, in a complex infinite dimensional Hilbert space H, this convergence result fails even for biholomorphic self-mappings of the Hilbert ball B_H ([56]; see also [19]). Stachura's example shows that in order to obtain a generalization of the Denjoy-Wolff theorem, we not only need additional properties of the boundary of the domain D, but we also have to impose some restrictions on the holomorphic self-mapping $F: D \to D$ itself. Therefore the following notions were introduced in [39] and [51, page 224]. Let B_H be the open unit ball in an infinite dimensional complex Hilbert space H. We say that a self-mapping F of B_H has the Denjoy-Wolff iteration property (DWIP) if F has no fixed point in B_H and for each $x \in B_H$, the sequence of iterates $\{F^n(x)\}$ strongly converges to a unique point ξ on the boundary ∂B_H of B_H . We will also say that a class \mathcal{G} of self-mappings of B_H has the Denjoy-Wolff iteration property if whenever $F \in \mathcal{G}$ has no fixed point in B_H , then for each $x \in B_H$, the sequence of iterates $\{F^n(x)\}$ strongly converges to a unique point ξ on the boundary ∂B_H of B_H . Next, a self-mapping F of B_H has the compact Denjoy-Wolff iteration property (cDWIP) if F has no fixed point in B_H and the sequence of iterates $\{F^n\}$ converges in the compact-open topology to a unique point ξ on the boundary ∂B_H of B_H . A class \mathcal{G} of self-mappings of B_H has the compactopen Denjoy-Wolff iteration property if each $F \in \mathcal{G}$ has the cDWIP. Finally, if a self-mapping F of B_H has no fixed point in B_H and the sequence of iterates $\{F^n\}$ converges uniformly on each closed ball $B(0,r) \subset B_H, 0 < r < 1$, to a unique point ξ on the boundary ∂B_H of B_H , then we say that F has the strong Denjoy-Wolff iteration property (sDWIP). A class \mathcal{G} of self-mappings of B_H has the strong Denjoy-Wolff iteration property if each $F \in \mathcal{G}$ has the sDWIP.

The following classes of self-mappings of B_H are known to have the Denjoy-Wolff iteration property:

1) ([30]; see also [7–9], [14, 29, 34] and [38]) the class \mathcal{G}_1 consisting of mappings which are condensing with respect to the Kuratowski measure of noncompactness ([43]; see also [4, 44] and [5]);

2) ([21,22,48] and [49]) the class \mathcal{G}_2 of firmly k_{B_H} -nonexpansive mappings of the first kind;

3) ([21,22,48] and [49]) the class \mathcal{G}_3 of firmly k_{B_H} -nonexpansive mappings of the second kind;

4) ([47]) the class \mathcal{G}_4 consisting of the averaged mappings of the first kind, that is, $F = (1-c)I \oplus cT$, where T is k_{B_H} -nonexpansive and $c \in (0,1)$ (see Theorem 2.2 below for the definition of the operation \oplus);

5) ([47]) the class \mathcal{G}_5 consisting of the averaged mappings of the second kind, that is, F = (1-c)I + cT, where T is k_{B_H} -nonexpansive and $c \in (0,1)$;

6) ([25,37] and [41]) the class \mathcal{G}_6 consisting of mappings F of $\overline{B_H}$ onto $\overline{B_H}$ which are k_{B_H} -isometries in B_H , have exactly two fixed points in $\overline{B_H}$ and these fixed points lie on the boundary ∂B_H .

In this paper we first present new conditions which are equivalent to the Denjoy-Wolff iteration property in the Hilbert ball B_H and then use them to find new classes of mappings with this property (see Section 3 below).

2. Preliminaries

We use the following concepts and notations. Let D_1 and D_2 be domains in the complex Banach spaces X_1 and X_2 , respectively. The set of all holomorphic mappings from D_1 into D_2 is denoted by $H(D_1, D_2)$. A mapping $f \in H(D_1, D_2)$ is said to be biholomorphic if $f(D_1) = D_2$, f is one-to one, and $f^{-1} \in H(D_2, D_1)$. If such a mapping exists, then we say that D_1 is biholomorphically equivalent to D_2 .

The Kobayashi distance ([31, 32] and [33]; see also [2, 21, 26] and [27]) plays an important role in the fixed point theory of holomorphic mappings. So first we recall its definition and a few of its important properties, which will be used in the proof of our theorems.

Let Δ be the open unit disc in the complex plane \mathbb{C} . The Poincaré distance $k_{\Delta} = \omega$ on Δ is given by

$$k_{\Delta}(z, w) = \omega(z, w) := \operatorname{arg tanh} \left| \frac{z - w}{1 - z\overline{w}} \right|$$
$$= \operatorname{arg tanh} (1 - \sigma(z, w))^{\frac{1}{2}},$$

where

$$\sigma\left(z,w\right) := \frac{\left(1 - |z|^2\right)\left(1 - |w|^2\right)}{\left|1 - z\overline{w}\right|^2}, \quad z, w \in \Delta$$

([22, 23] and [51]).

Next, we recall the Lempert function.

Definition 2.1 ([45]). The Lempert $\delta : D \to [0, \infty)$ is defined by the following formula:

$$\delta_D(x, y) := \inf \left\{ \omega(0, \lambda) : \lambda \in [0, 1) \text{ and there exists } f \in H(\Delta, D) \right\}$$

so that $f(0) = x$ and $f(\lambda) = y$,

where $x, y \in D$.

Definition 2.2 ([31,32] and [33]). Let D be a domain in a Banach space X. The Kobayashi pseudodistance k_D in D is defined by

$$k_D(x,y) := \inf \left\{ \sum_{j=1}^n \delta_D(x_j, x_{j+1}) : n \in \mathbb{N}, \{x = x_1, ..., x_{n+1} = y\} \subset D \right\}.$$

Now we recall connections between holomorphic mappings and the Kobayashi pseudodistances. Namely, if D_1 and D_2 are domains in the complex Banach spaces X_1 and X_2 , respectively, then each holomorphic mapping $f: D_1 \to D_2$ is nonexpansive, that is,

$$k_{D_2}(f(x), f(y)) \le k_{D_1}(x, y)$$

for all $x, y \in D_1$ ([31, 32] and [33]; see also [22, 24, 38] and [51]).

Observe that if D_1 is biholomorphically equivalent to D_2 by the biholomorphic function $f: D_1 \to D_2$, then

$$k_{D_2}(f(x), f(y)) = k_{D_1}(x, y)$$

for all $x, y \in D_1$.

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Next, if D is a domain in a complex Banach space X and a mapping $f: D \to D$ satisfies

$$k_D(f(x), f(y)) \le k_D(x, y)$$

for all $x, y \in D$, then f is called k_D -nonexpansive ([20]). Directly from this definition we get that if D_1 is biholomorphically equivalent to D_2 , by the biholomorphic mapping $f: D_1 \to D_2$, then a mapping $g: D_1 \to D_1$ is k_{D_1} -nonexpansive if and only if the mapping $h := f \circ g \circ f^{-1}: D_2 \to D_2$ is k_{D_2} -nonexpansive.

If the Kobayashi pseudodistance k_D is a metric in the topological sense, then it is called the *Kobayashi distance*. For example, if D is a bounded and convex domain, then k_D is the Kobayashi distance which coincides with the Lempert function δ_D ([17] and [45]).

In general, there are no explicit formulae for the Kobayashi pseudodistance k_D of domains D. However, in the case of the Hilbert ball B_H , we do have the following explicit formula for the Kobayashi distance k_{B_H} . Namely,

$$k_{B_H}(x,y) = \operatorname{arg\,tanh}\left(1 - \sigma\left(x,y\right)\right)^{\frac{1}{2}},$$

where $x, y \in B_H$ and

$$\sigma(x,y) = \frac{\left(1 - \|x\|^2\right)\left(1 - \|y\|^2\right)}{\left|1 - (x,y)\right|^2}$$

where (\cdot, \cdot) is the inner product in the Hilbert space H ([22] and [23]).

Observe that if Δ is the open unit disc in the complex plane \mathbb{C} , then the Kobayashi distance k_{Δ} is simply the Poincaré distance on Δ .

Now we recall the following very important property of the Kobayashi distance k_{B_H} .

Lemma 2.3 ([22] and [24]). The Kobayashi distance k_{B_H} is locally equivalent to the norm $\|\cdot\|$ in the Hilbert space H, that is, the following inequalities are valid: (i)

$$\operatorname{arg\,tanh}\left(\frac{\|x-y\|}{2}\right) \le k_{B_H}(x,y)$$

for all $x, y \in B_H$; (ii)

$$k_{B_H}(x,y) \le rg anh\left(\frac{\|x-y\|}{\operatorname{dist}_{\|\cdot\|}(x,\partial B_H)}\right)$$

whenever $||x - y|| < \operatorname{dist}_{||\cdot||}(x, \partial B_H)$, where

$$\operatorname{dist}_{\|\cdot\|}(x,\partial B_H) := \inf\{\|x-y\| : y \in \partial B_H\}.$$

Next, we present further properties of the distance k_{B_H} .

Theorem 2.4. The metric space (B_H, k_{B_H}) has the following properties:

(i) ([23] and [22]) For each pair of distinct points $x, y \in B_H$, there exist a unique geodesic line passing through them and a unique geodesic segment [x, y] joining them. For each $0 \le t \le 1$, there is a unique point $z = (1 - t) x \oplus ty$ satisfying $k_{B_H}(x, z) = tk_{B_H}(x, y)$ and $k_{B_H}(z, y) = (1 - t) k_{B_H}(x, y)$.

(ii) ([22]) If
$$x, y, w$$
 and z are in B_H and $0 \le t \le 1$, then

$$k_{B_H}((1-t)\,x\oplus tw,(1-t)\,x\oplus tz) \le tk_{B_H}(w,z)$$

and

$$k_{B_H}((1-t)\,x \oplus tw, (1-t)\,y \oplus tz) \le (1-t)\,k_{B_H}(x,y) + tk_{B_H}(w,z).$$

Strict inequalities occur if 0 < t < 1 and the relevant points do not lie on the same geodesic.

(iii) ([23] and [22]) The metric space (B_H, k_{B_H}) has the Opial property with respect to the weak topology in H ([46]), that is, if a k_{B_H} -bounded sequence $\{x_n\}$ in B_H tends weakly to $x \in B_H$, then

$$\limsup_{n} k_{B_H}(x_n, x) < \limsup_{n} k_{B_H}(x_n, y)$$

for each $y \in B_H \setminus \{x\}$.

(iv) ([28] and [36]) Let $\{x_n\}$ and $\{y_n\}$ be two sequences in B_H and let $\{x_n\}$ converge strongly to $\xi \in \partial B_H$. If

$$\sup \left\{ k_D\left(x_n, y_n\right) : n \in \mathbb{N} \right\} = c < \infty,$$

then $\{y_n\}$ is also strongly convergent to ξ .

Before reviewing a few results from the fixed point theory of holomorphic selfmappings of B_H (or, more generally, k_{B_H} -nonexpansive self-mappings of B_H), we recall the following notion. A mapping $T: B_H \to B_H$ is said to map B_H strictly inside B_H if $\sup_{x \in B_H} ||T(x)|| < 1$. Now we are ready to present the Earle-Hamilton theorem for B_H .

Theorem 2.5 ([18] (see also [52] and [53])). If a holomorphic $T : B_H \to B_H$ maps B_H strictly inside itself, then there exists a number $0 \le s < 1$ such that

$$k_{B_H}(T(x), T(y)) \le sk_{B_H}(x, y)$$

for all $x, y \in B_H$, and therefore T has a unique fixed point. Moreover, for each $x \in B_H$, the sequence of its iterates $\{T^n(x)\}$ converges to this point.

Using Theorems 2.4 and 2.5 and the explicit formula for the Kobayashi distance k_{B_H} , we get the following fixed point theorem for the Hilbert ball.

Theorem 2.6 ([22,23,40] and [35]). Let $T : B_H \to B_H$ be a holomorphic mapping or, more generally, a k_{B_H} -nonexpansive mapping. Then the following statements are equivalent:

- (i) T has a fixed point.
- (ii) For each point $x \in B_H$, the sequence of its iterates $\{T^n(x)\}$ lies strictly inside B_H (this means that $\{T^n(x)\}$ is k_{B_H} -bounded).
- (iii) There exists a ball B(x,r) in (B_H, k_{B_H}) which is T-invariant.
- (iv) There exists a nonempty, k_{B_H} -bounded, k_{B_H} -closed and k_{B_H} -convex subset of B_H which is T-invariant.
- (v) There exists a nonempty, k_{B_H} -bounded, k_{B_H} -closed and convex subset of B_H which is T-invariant.
- (vi) There exists a k_{B_H} -bounded sequence $\{x_n\}$ in B_H with $x_n T(x_n) \to 0$.

When we study the behavior of iterates of k_{B_H} -nonexpansive mappings, then the following theorem is very useful.

Theorem 2.7 ([23] and [22]; see also [1,2,50,51] and [60]). If a k_{B_H} -nonexpansive mapping $T : B_H \to B_H$ is fixed point free, then there exists a unique point ξ_T of norm one such that all the "ellipsoids"

$$E\left(\xi_{T}, R\right) := \left\{ x \in B_{H} : \frac{\left|1 - (x, \xi_{T})\right|^{2}}{1 - \left\|x\right\|^{2}} < R \right\}, \quad R > 0,$$

are invariant under T, $\overline{E(\xi_T, R)} \cap \partial B_H = \{\xi_T\}$ and for every $x \in B_H$, there exists R > 0 such that $x \in E(\xi_T, R)$. Moreover, all the approximating curves defined by

$$w_a(t) := (1-t) a \oplus tT(w_a(t))$$

and

$$z_a(t) := (1-t)a + tT(z_a(t))$$

where $t \in [0,1)$ and $a \in B_H$, converge strongly to ξ_T as $t \to 1^-$.

Directly from Theorems 2.4–2.7 and the explicit formula for k_{B_H} we get the following corollary.

Corollary 2.8 ([47]). Let B_H be the Hilbert ball and let $T : B_H \to B_H$ be k_{B_H} nonexpansive. If T is fixed point free and $\lim_n ||T^n(\tilde{x})|| = 1$ for some $\tilde{x} \in B_H$, then T has the DWIP.

At this point we need the notions of total boundedness and finite total boundedness of a metric space. Recall that a metric space is said to be totally bounded if for each $\varepsilon > 0$, it can be decomposed into a finite number of sets of diameter $< \varepsilon$ ([43]; see also [44]). We also say that a metric space is finitely totally bounded if each nonempty and bounded subset of X is totally bounded. Now we are able to recall Całka's theorem regarding the behavior of the sequence of iterates of a nonexpansive mapping on a finitely totally bounded metric space X.

Theorem 2.9 ([12]). Let f be a nonexpansive mapping of a finitely totally bounded metric space X into itself. If for some $x_0 \in X$, the sequence $\{f^n(x_0)\}$ contains a bounded subsequence, then for each $x \in X$, the sequence $\{f^n(x)\}$ is bounded.

3. Main result

In this section we present the main result of our paper and some of its applications. First we observe the following fact.

Theorem 3.1. Let B_H be the Hilbert ball and let $T : B_H \to B_H$ be k_{B_H} -nonexpansive. Then the following statements are equivalent:

- 1) T has the DWIP.
- 2) T has the cDWIP.
- 3) T has the sDWIP.

Proof. The implications $3) \Rightarrow 2$ and $2) \Rightarrow 1$ are obvious. To get the implication $1) \Rightarrow 3$, it is sufficient to apply Theorem 2.4 *(iv)* and the inequality

$$k_{B_H}(T^n(x), T^n(y)) \le k_{B_H}(x, y),$$

which is valid for all $n \in \mathbb{N}$ and all $x, y \in B_H$.

Now we are ready to state and prove the main theorem of our paper.

Theorem 3.2. Let B_H be the Hilbert ball and let $T : B_H \to B_H$ be k_{B_H} -nonexpansive. The following statements are equivalent:

- 1) T has the DWIP.
- 2) There exists a point $\tilde{x} \in B_H$ such that $\lim_n ||T^n(\tilde{x})|| = 1$.
- 3) There exists a point $\tilde{x} \in B_H$ such that the sequence of its iterates $\{T^n(\tilde{x})\}$ is relatively compact in the Hilbert space H and $\limsup_n ||T^n(\tilde{x})|| = 1$.
- 4) T has no fixed point and there exists a point $\tilde{x} \in B_H$ such that the sequence of its iterates $\{T^n(\tilde{x})\}$ is relatively compact in the Hilbert space H.

Proof. The implications $1) \Rightarrow 2$ and $1) \Rightarrow 3$ are obvious. Next, it follows from Theorem 2.6 *(ii)* and Corollary 2.8 that $2) \Rightarrow 1$ and by Theorem 2.9 we get $3) \Rightarrow 2$. Finally, using Theorem 2.6 *(ii)*, we obtain $3) \Leftrightarrow 4$.

Before presenting a few applications of this theorem, we recall that the Hilbert ball B_H is biholomorfically equivalent to the Siegel upper half-space Ω ([13, 22, 54] and [56]). Indeed, let B_H be the open unit ball in the complex infinite-dimensional Hilbert space H and let e be a vector in H of norm 1. Then the Hilbert space Hcan be written as the orthogonal direct sum decomposition $\mathbb{C} \times H^{\perp}$, where H^{\perp} is the subspace of H orthogonal to e with codimension 1, that is,

$$H \ni w = \lambda e + w' = (\lambda, w') \in \mathbb{C} \times H^{\perp}.$$

The Hilbert ball B_H is biholomorphically equivalent to the domain

$$\Omega := \left\{ w = (\lambda, w') \in \mathbb{C} \times H^{\perp} : \operatorname{Im} \lambda > \left\| w' \right\|^2 \right\}$$

by the Cayley transform $\mathcal{C}: B_H \to \Omega$ given by

$$B_H \ni z = (\xi, z') \mapsto \mathcal{C}(z) = \mathcal{C}(\xi, z') = \left(i\frac{1+(z,e)}{1-(z,e)}, \frac{i(z-(z,e)e)}{1-(z,e)}\right) \\ = \left(i\frac{1+\xi}{1-\xi}, \frac{iz'}{1-\xi}\right) = (\lambda, w') = w \in \Omega.$$

As mentioned above, the mapping C is invertible and

$$z = (\xi, z') = \mathcal{C}^{-1}(w) = \mathcal{C}^{-1}(\lambda, w') = \frac{2w}{\lambda + i} - e = \left(\frac{\lambda - i}{\lambda + i}, \frac{2w'}{\lambda + i}\right).$$

Observe that the boundary of Ω in H is given by

$$\partial\Omega = \left\{ w = (\lambda, w') \in \mathbb{C} \times H^{\perp} : \operatorname{Im} \lambda = \left\| w' \right\|^2 \right\}$$

and therefore $\overline{\Omega} = \Omega \cup \partial_H \Omega$ is the closure of Ω in H. If we add ∞ to H and introduce a basis for the open neighborhoods of ∞ in $H \cup \{\infty\}$ by $\{x \in H : ||x|| > \varepsilon\}$, where

 $\varepsilon > 0$, then the closure $\overline{\Omega}^{\infty}$ of Ω in $H \cup \{\infty\}$ is equal to $\overline{\Omega} \cup \{\infty\}$. Next, we extend the Cayley transform \mathcal{C} to the closure of B_H by setting

$$\overline{B_H} \setminus \{e\} \ni z = (\xi, z') \to \mathcal{C}(z) = \mathcal{C}\left(\xi, z'\right) = \left(i\frac{1+(z,e)}{1-(z,e)}, \frac{i(z-(z,e)e)}{1-(z,e)}\right)$$
$$= \left(i\frac{1+\xi}{1-\xi}, \frac{iz'}{1-\xi}\right) = (\lambda, w') = w \in \overline{\Omega}$$

and

$$\mathcal{C}\left(e\right)=\infty$$

Then this extended Cayley transform $\mathcal{C}: \overline{B_H} \to \overline{\Omega}^{\infty}$ is also invertible and $\mathcal{C}^{-1}: \overline{\Omega}^{\infty} \to \overline{B_H}$ is given by the following formula:

$$\overline{\Omega} \ni z = (\xi, z') = \mathcal{C}^{-1}(w) = \mathcal{C}^{-1}(\lambda, w') = \frac{2w}{\lambda + i} - e = \left(\frac{\lambda - i}{\lambda + i}, \frac{2w'}{\lambda + i}\right) \in \overline{B_H} \setminus \{e\}$$

and

$$\mathcal{C}^{-1}(\infty) = e$$

Both mappings \mathcal{C} and \mathcal{C}^{-1} are continuous in $H \cup \{\infty\}$. Observe that if Y is a finitedimensional subspace of H with $e \in Y$, then $B_Y := B_H \cap Y$ is biholomorphically equivalent to $\Omega_Y := \Omega \cap Y$ by the Cayley transform \mathcal{C} restricted to B_Y , and $\overline{B_Y}^H$ is isomorphic to $\overline{\Omega_Y}^{\infty} = \overline{\Omega_Y} \cup \{\infty\}$ by the Cayley transform \mathcal{C} .

Next, if a set $A \subset \Omega$ is relatively compact in H, then its image $\mathcal{C}^{-1}(A) \subset B_H$ is also relatively compact in H.

Now we are ready to formulate the following Denjoy-Wolff theorem for holomorphic self-mappings of Ω or, more generally, k_{Ω} -nonexpansive self-mappings of Ω . This theorem is a direct consequence of Theorem 3.2 and the above remarks regarding the Cayley transform \mathcal{C} and its extension.

Theorem 3.3. Let $f : \Omega \to \Omega$ be k_{Ω} -nonexpansive. The following statements are equivalent:

- I) The sequence of iterates $\{f^n\}$ converges pointwise to a point $\tilde{\xi}$ on the boundary $\partial_{\infty}\Omega = \partial\Omega \cup \{\infty\}$ of Ω in $\overline{\Omega}^{\infty}$.
- II) For some $\tilde{w} \in \Omega$, the sequence of its iterates $\{f^n(\tilde{w})\}$ converges to a point $\tilde{\xi}$ on the boundary $\partial_{\infty}\Omega$ of Ω .
- III) There exists $\tilde{w} \in \Omega$ such that the sequence of its iterates $\{f^n(\tilde{w})\}\$ is either relatively compact in the Hilbert space H and

 $\liminf_{n} \operatorname{dist}(\{f^{n}(\tilde{w})\}, \partial_{H}\Omega) = \inf\{\|f^{n}(\tilde{w}) - w\| : n \in \mathbb{N}, w \in \partial_{H}\Omega\} = 0,$

 $or \lim_n \|f^n(\tilde{w})\| = +\infty.$

IV) Either f has no fixed point and there exists $\tilde{w} \in \Omega$ such that the sequence of its iterates $\{f^n(\tilde{w})\}$ is relatively compact in the Hilbert space H or there exists $\tilde{w} \in \Omega$ such that $\lim_n ||f^n(\tilde{w})|| = +\infty$.

As a direct consequence of the above theorem we get the following corollary.

Corollary 3.4. If $f: \Omega \to \Omega$ is fixed point free and there exists a finite-dimensional subspace Y of H such that the set $\Omega_Y = \Omega \cap Y$ is f-invariant, then for each $w \in \Omega$, the sequence of its iterates $\{f^n(w)\}$ converges to a unique point $\tilde{\xi}$ on the boundary $\partial_{\infty}\Omega$ of Ω .

Hence if $f: \Omega \to \Omega$ satisfies one of the condition given in Theorem 3.3, then we see that the mapping $T = \mathcal{C}^{-1} \circ f \circ \mathcal{C} : B_H \to B_H$ has the DWIP.

Next, observe that sometimes it is easier to construct a function $f: \Omega \to \Omega$ such that the mapping $T = \mathcal{C}^{-1} \circ f \circ \mathcal{C} : B_H \to B_H$ has the claimed properties, than it is to seek such a function directly in B_H .

Now we are ready to present a few examples of mappings $f: \Omega \to \Omega$ which satisfy the conditions given either in Theorem 3.3 or in Corollary 3.4. Among them there are functions f such that the mappings $T = \mathcal{C}^{-1} \circ f \circ \mathcal{C}$ are not elements of any of the classes $\mathcal{G}_j, j = 1, ..., 6$, mentioned in the Introduction.

Example 3.5. The mapping $f: \Omega \to \Omega$ is a translation defined by

$$f(w) = f(\lambda, w') = (\lambda + a, w')$$

for $w \in \Omega$, where a is a nonzero real number. The mapping f has no fixed points and $f(\Omega_{\text{lin}\{e\}})$ is a subset of $\Omega_{\text{lin}\{e\}}$.

As a matter of fact, we can present more general mappings of the above type.

Example 3.6. Let $\varphi : H^{\perp} \to H^{\perp}$ be holomorphic with $\|\varphi(w')\| \leq \|w'\|$ for each $w' \in H^{\perp}$. The mapping $f : \Omega \to \Omega$ is of the form

$$f(w) = f(\lambda, w') = (\lambda + a, \varphi(w')), \quad w \in \Omega,$$

where a is a nonzero real number. Assume that there exists a finite-dimensional subspace Y of H^{\perp} such that the set Ω_Y is φ -invariant. It is obvious that f is fixed point free.

Example 3.7. Let $\varphi : H^{\perp} \to H^{\perp}$ be holomorphic with $\|\varphi(w')\| \leq \|w'\|$ for each $w' \in H^{\perp}$. The mapping $f : \Omega \to \Omega$ is of the form

$$f(w) = f(\lambda, w') = (\lambda + ia, \varphi(w')), \quad w \in \Omega,$$

where a is a positive real number and there exists a finite-dimensional subspace Y of H^{\perp} such that the set Ω_Y is φ -invariant. It is obvious that f is fixed point free.

Example 3.8. The mapping $f: \Omega \to \Omega$ is defined by

$$f(w) = f(\lambda, w') = (\lambda + i(||a||^2 + 2(w', a)), w' + a), \quad w \in \Omega,$$

where a is a nonzero element of H^{\perp} . It is not difficult to note that the sequence of iterates $\{\varphi\}^n(i,0)$ lies in a two dimensional subspace of H and f has no fixed points.

Example 3.9. Let $\varphi : H^{\perp} \to H^{\perp}$ be holomorphic with $\|\varphi(w')\| \leq \|w'\|$ for each $w' \in H^{\perp}$. Assume that there exists $0 \neq a \in H^{\perp} \setminus \varphi(H^{\perp})$. Then the mapping $f : \Omega \to \Omega$ given by

$$f(w) = f(\lambda, w') = (\lambda + i ||a||^2, \varphi(w') + a), \quad w \in \Omega,$$

has no fixed points. Let $\Phi(w') = \varphi(w') + a$. Now it is sufficient to assume that for some $w' \in H^{\perp}$, the sequence of its iterates $\{\Phi\}^n(w')$ lies in a finite-dimensional subspace of H^{\perp} to get a mapping $T := \mathcal{C}^{-1} \circ f \circ \mathcal{C} : B_H \to B_H$ with the DWIP. **Example 3.10.** Consider the "nonisotropic" dilation $D_t : \Omega \to \Omega$ introduced in the following way:

$$D_t(w) = D_t(\lambda, w') = (t^2\lambda, tw'), \quad w \in \Omega,$$

where $0 < t < \infty$ is a fixed constant ([54]). This holomorphic automorphism D_t is the analog of the Möbius transformation $M_{se}: B_H \to B_H$ with $-1 < s = \frac{t^2-1}{t^2+1} < 1$, where

$$M_{se}(z) = M_{se}(\xi, z') = \frac{1}{1+s\xi}(\xi+s, \sqrt{1-s^2}z')$$

for $z = (\xi, z') \in B_H$. The mapping D_t can be continuously extended to $\overline{\Omega}^{\infty}$ and for $t \neq 1$ this extended mapping D_t fixes only 0 and ∞ . We also have $D_t(\Omega_{\min\{e\}}) = \Omega_{\min\{e\}}$.

The last example yields a mapping $T := \mathcal{C}^{-1} \circ f \circ \mathcal{C} : \overline{B_H} \to \overline{B_H}$ $(t > 0 \text{ and } t \neq 1)$, which is a particular case of the following one.

Example 3.11. Let T be a mapping of $\overline{B_H}$ onto $\overline{B_H}$ which is a k_{B_H} -isometry in B_H , has exactly two fixed points in $\overline{B_H}$, and these fixed points lie on the boundary ∂B_H of B_H . Then there exists a 2-dimensional T-invariant affine set in B_H and therefore the mapping T has the DWIP by Theorem 3.2 (see also example 6 in the Introduction).

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