

UNIFORMLY LIPSCHITZIAN MAPPINGS IN \mathbb{R} -TREES

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Dedicated to Wataru Takahashi on the occasion of his 70th birthday

ABSTRACT. Let (X, ρ) be a complete \mathbb{R} -tree, and suppose $T : X \rightarrow X$ has bounded orbits and satisfies for all $n \in \mathbb{N}$ sufficiently large,

$$\rho(T^n x, T^n y) \leq k_n \rho(x, y),$$

for all $x, y \in X$. A. Aksoy and M. A. Khamsi [Sci. Math. Jpn. 65(2007), 31-41, e:2006, 1143-1153] have shown that if $\limsup_{n \rightarrow \infty} k_n < 2$ then T has a fixed point. The main result of this paper shows that if, in addition, T is assumed to be continuous, then it suffices merely to assume that $\limsup_{n \rightarrow \infty} k_n < \infty$.

1. INTRODUCTION

Let (X, ρ) be a metric space. The balls in X are said to be *c-regular* for $c \geq 1$ if the following holds: For any $k < c$ there exist numbers $\mu, \alpha \in (0, 1)$ such that for any $x, y \in X$ and $r > 0$ with $\rho(x, y) \geq (1 - \mu)r$, there exists $z \in X$ such that

$$B(x; (1 + \mu)r) \cap B(y; k(1 + \mu)r) \subseteq B(z; \alpha r).$$

The Lifšic constant $\kappa(X)$ of X is the number

$$\kappa(X) = \sup \{c \geq 1 : \text{the balls in } X \text{ are } c\text{-regular}\}.$$

Lifšic proved in [11] that if (X, ρ) is a bounded complete metric space, and if for some $k < \kappa(X)$, $T : X \rightarrow X$ satisfies

$$\rho(T^n x, T^n y) \leq k \rho(x, y)$$

for all $x, y \in X$ and $n \in \mathbb{N}$, then T has a fixed point.

A related result for an \mathbb{R} -tree (defined below) is found in [1], where it is shown that if (X, ρ) is a complete \mathbb{R} -tree, and if $T : X \rightarrow X$ has bounded orbits and satisfies for all $n \in \mathbb{N}$ sufficiently large,

$$\rho(T^n x, T^n y) \leq k_n \rho(x, y),$$

for all $x, y \in X$, where $\limsup_{n \rightarrow \infty} k_n < 2$, then T has a fixed point.

Our objective in this note is to extend both the Lifšic and Aksoy-Khamsi results. In particular we show that Lifšic's assumption $\rho(T^n x, T^n y) \leq k \rho(x, y)$ can be replaced with the weaker assumption $\rho(T^n x, T^n y) \leq k_n \rho(x, y)$ where

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$\limsup_{n \rightarrow \infty} k_n < \kappa(X)$. Regarding the Aksoy-Khamsi result, we show that if T is continuous, $\limsup_{n \rightarrow \infty} k_n < 2$ can be replaced with the much weaker assumption $\limsup_{n \rightarrow \infty} k_n < \infty$.

2. THE LIFSIC EXTENSION

Theorem 2.1 (Lifsic). *Suppose (X, ρ) is a complete metric space, and suppose $T : X \rightarrow X$ has bounded orbits and satisfies for all $n \in \mathbb{N}$ sufficiently large,*

$$(2.1) \quad \rho(T^n x, T^n y) \leq k_n \rho(x, y)$$

for all $x, y \in X$, with $\limsup_{n \rightarrow \infty} k_n < \kappa(X)$. Then T has a fixed point.

Proof. (Except for the final paragraph, this is identical to the proof given in [7, p. 172].) If $\kappa(X) = 1$ then, for sufficiently large n , T^n is a contraction mapping and there is nothing to prove. So, suppose $\kappa(X) > 1$. For each $x \in X$, set

$$r(x) = \inf \{r > 0 : B(x; r) \text{ contains an orbit of } T\}.$$

Now let $\limsup_{n \rightarrow \infty} k_n < k < \kappa(X)$, and let $\mu, \alpha \in (0, 1)$ be the numbers associated with k in the definition of k -regular balls. Then given any $x \in X$ there is an integer $m \in \mathbb{N}$ such that

$$\rho(x, T^m x) \geq (1 - \mu)r(x)$$

and there is also a point $y \in X$ such that

$$\rho(x, T^n y) \leq (1 + \mu)r(x), \quad n = 1, 2, \dots$$

Since the balls are k -regular there exists $z \in X$ and $\alpha < 1$ such that

$$D := B(x; (1 + \mu)r(x)) \cap B(T^m x; k(1 + \mu)r(x)) \subseteq B(z; \alpha r(x)).$$

Next observe that for m sufficiently large,

$$\rho(T^m x, T^n y) \leq k\rho(x, T^{n-m} y) \leq k(1 + \mu)r(x).$$

for all $n > m$. This shows that $\{T^n y\}_{n > m}$ is contained in D , and hence in $B(z; \alpha r(x))$. This in turn implies that

$$r(z) \leq \alpha r(x).$$

Also, for any $u \in D$,

$$\begin{aligned} \rho(z, x) &\leq \rho(z, u) + \rho(u, x) \\ &\leq \alpha r(x) + (1 + \mu)r(x) \\ &= Ar(x) \end{aligned}$$

where $A = \alpha + 1 + \mu$.

By setting $x = x_0$ and $z = z(x_0)$, it is possible to define a sequence $\{x_n\}$ with $x_{n+1} = z(x_n)$, where $z(x_n)$ is defined via the above procedure. Thus $r(x_n) \leq \alpha^n r(x_0)$ and $\rho(x_n, x_{n+1}) \leq Ar(x_n) \leq \alpha^n r(x_0)$. This proves that $\{x_n\}$ is a Cauchy sequence which has limit, say x^* . Now choose $N \in \mathbb{N}$ so that both T^N and T^{N+1} are Lipschitzian. Since $B(x^*; \varepsilon)$ contains an orbit of T for any $\varepsilon > 0$ there exists a sequence $\{y_n\}$ also converging to x^* for which $\lim_{n \rightarrow \infty} \rho(T^N y_n, T^{N+1} y_n) = 0$. It follows that $T^N x^* = T^{N+1} x^*$; hence $T^N x^*$ is a fixed point of T . \square

For most metric spaces M , $\kappa(M) = 1$ and for such spaces Lifšic's theorem is equivalent to the Banach Contraction Principle. However as we observe below there are spaces for which $\kappa(M) > 1$.

Now let X be a Banach space. We define the *uniform Lifšic constant*, $\kappa_0(X)$, of X as follows

$$\kappa_0(X) = \sup \left\{ c \geq 1 : \begin{array}{l} \exists \alpha < 1 \text{ such that } \forall x, \|x\| \leq 1, \exists \lambda \in [0, 1] \\ \text{such that } B(0; 1) \cap B(x; c) \subset B(\lambda x; \alpha) \end{array} \right\}.$$

Lifšic proved that $\kappa_0(H) \geq \sqrt{2}$ if H is a Hilbert space, and this estimate is sharp.

The Lifšic constant is also known to be larger than one in certain geodesic spaces, specifically the class of geodesic spaces called the $CAT(\kappa)$ spaces for $\kappa \leq 0$. A geodesic space (X, d) is said to be a $CAT(\kappa)$ space (the term is due to M. Gromov—see, e.g., [2], p. 159) if it is geodesically connected and has constant curvature bounded above by κ . More precisely, every geodesic triangle in X is at least as ‘thin’ as its comparison triangle in M_κ^2 , where for $\kappa < 0$ M_κ^2 is the real hyperbolic space \mathbb{H}^2 with the distance function scaled by a factor of $1/\sqrt{-\kappa}$, and if $\kappa = 0$, M_κ^2 is the Euclidean plane. For precise definitions and a thorough discussion of these spaces and of the fundamental role they play in various branches of mathematics, see Bridson and Haefliger [2] or Burago, et al. [3]. We note in particular that the complex Hilbert ball with a hyperbolic metric (see [8]; also inequality (4.3) of [12] and subsequent comments) is a $CAT(0)$ space.

There are interesting spaces which are $CAT(\kappa)$ for all $\kappa \leq 0$.

Definition 2.2. An \mathbb{R} -tree (or metric tree) is a metric space M such that

- (i) there is a unique geodesic (metric) segment denoted by $[x, y]$ joining each pair of points x and y in M ; and
- (ii) $[y, x] \cap [x, z] = \{x\} \Rightarrow [y, x] \cup [x, z] = [y, z]$.

In [5] it was proved that the Lifšic constant $\kappa(X)$ for any $CAT(\kappa)$ space X with $\kappa \leq 0$ satisfies $\kappa(X) \geq \sqrt{2}$, and $\kappa(X) = 2$ if X is an \mathbb{R} -tree.

In view of this observation and Theorem 2.1 we have the following:

Theorem 2.3. *Let (X, ρ) be a complete $CAT(0)$, and let $T : X \rightarrow X$ have bounded orbits and satisfies for all $n \in \mathbb{N}$ sufficiently large,*

$$\rho(T^n x, T^n y) \leq k_n \rho(x, y)$$

for all $x, y \in X$, where $\limsup_{n \rightarrow \infty} k_n < \sqrt{2}$. Then T has a fixed point.

In view of the fact that $\kappa(X) = 2$ if X is an \mathbb{R} -tree, Theorem 2.1 also yields the following result of Aksoy and Khamsi.

Theorem 2.4 ([1]). *Let (X, ρ) be a complete \mathbb{R} -tree, and suppose $T : X \rightarrow X$ has bounded orbits and satisfies for all $n \in \mathbb{N}$ sufficiently large,*

$$\rho(T^n x, T^n y) \leq k_n \rho(x, y),$$

for all $x, y \in X$, where $\limsup_{n \rightarrow \infty} k_n < 2$. Then T has a fixed point.

Question 1. It is natural to ask whether 2 the optimal constant for Theorem 2.4.

In the next section we show that the answer to Question 1 in some spaces is ‘no’. We also show that if T is *continuous* the assumption $\limsup_{n \rightarrow \infty} k_n < 2$ may be remarkably relaxed. In this case it is enough to assume $\lim_{n \rightarrow \infty} k_n < \infty$. This is the main result of the paper.

3. AN \mathbb{R} -TREE EXTENSION

Throughout this section we use $O(x)$ to denote the orbit of a mapping $T : X \rightarrow X$ at a point $x \in X$; thus $O(x) = \{x, Tx, T^2x, \dots\}$.

Our extension of Theorem 2.4 is an application of the following fundamental fact. For a proof see [9].

Theorem 3.1. *Every continuous mapping T of a complete geodesically bounded \mathbb{R} -tree X into itself has a fixed point.*

We should remark that Theorem 3.1 is actually a special case of a theorem of G. S. Young [13]. For further discussion see [10].

Theorem 3.2. *Let (X, ρ) be a complete \mathbb{R} -tree. Suppose $T : X \rightarrow X$ is continuous and has bounded orbits, and suppose for all $n \in \mathbb{N}$ sufficiently large,*

$$(3.1) \quad \rho(T^n x, T^n y) \leq k_n \rho(x, y)$$

for all $x, y \in X$, with $\limsup_{n \rightarrow \infty} k_n < \infty$. Then some bounded convex subset of X is T -invariant; hence T has a fixed point.

This will be an immediate consequence of Theorem 3.1 and the following result.

Theorem 3.3. *Let (X, ρ) be an \mathbb{R} -tree. Suppose $T : X \rightarrow X$ is continuous and has bounded orbits, and suppose for all $n \in \mathbb{N}$ sufficiently large,*

$$(3.2) \quad \rho(T^n x, T^n y) \leq k_n \rho(x, y)$$

for all $x, y \in X$, with $\limsup_{n \rightarrow \infty} k_n < \infty$. Then some bounded subtree of X is T -invariant.

Proof. Fix $x \in X$ and choose $m \in \mathbb{N}$ and $k > 0$ with $\limsup_{n \rightarrow \infty} k_n < k$ so that $\rho(T^n u, T^n v) \leq k \rho(u, v)$ for all $u, v \in [x, Tx]$ and $n \geq m$. Let $Y = \bigcup_{i=1}^{\infty} T^i([x, Tx])$. Since each $T^i([x, Tx])$ is an arcwise connected subset of X , Y is an arcwise connected subset of X ; hence Y itself is an \mathbb{R} -tree which is clearly T -invariant. We show that Y is bounded.

Let $\xi(z) = \sup \{\rho(z, T^n z) : n \geq m\}$ for each $z \in [x, Tx]$. By assumption $\xi(z) < \infty$ for each $z \in [x, Tx]$. If $z, w \in [x, Tx]$ then

$$\begin{aligned} \rho(w, T^n w) &\leq \rho(w, z) + \rho(z, T^n z) + \rho(T^n z, T^n w) \\ &\leq \rho(w, z) + \xi(z) + k \rho(z, w) \end{aligned}$$

for each $n \geq m$. Thus $\xi(w) \leq \xi(z) + (1+k)\rho(z, w)$. Reversing the roles of z and w , we conclude

$$|\xi(z) - \xi(w)| \leq (1+k)\rho(z, w)$$

for all $z, w \in [x, Tx]$. Thus ξ is continuous, and since $[x, Tx]$ is compact,

$$\xi := \sup \{\xi(z) : z \in [x, Tx]\} < \infty.$$

Now for $1 \leq i < m$, let $m_i = \sup \{ \rho(z, T^i z) : z \in [x, Tx] \}$ and let

$$\beta = \max \{ m_i : i = 1, \dots, m - 1 \}.$$

Since T is continuous, $\beta < \infty$. Also, by construction, given $y \in Y$ there is at least one point $z \in [x, Tx]$ such that $y \in O(z)$. It follows that $\rho(z, y) \leq \beta + \xi$. Therefore Y is bounded. Specifically, $Y \subset B(x; d)$ where $d = \rho(x, Tx) + \beta + \xi$. \square

Since a nonexpansive mapping satisfies (3.1) for $k_n \equiv 1$ we have the following corollary.

Corollary 3.4 (Theorem 4.5 (i) of [6]). *A nonexpansive mapping of a complete \mathbb{R} -tree into itself with bounded orbits always has a fixed point.*

Remark 3.5. Under the assumptions of Theorem 3.2 it is enough to assume that one orbit of T is bounded. Indeed, the following is true.

Proposition 3.6. *Let (X, ρ) be a metric space and suppose $T : X \rightarrow X$ has a bounded orbit. Suppose that for all n sufficiently large,*

$$\rho(T^n x, T^n y) \leq k_n \rho(x, y)$$

for all $x, y \in X$. Suppose also that $\limsup_{n \rightarrow \infty} k_n < \infty$. Then all orbits of T are bounded.

Proof. Assume there exist $x \in X$ and $r > 0$ such that $O(x) \subset B(x; r)$. Choose $k > 0$ so that $\limsup_{n \rightarrow \infty} k_n < k$. Then if $y \in X$ it is possible to choose $m \in \mathbb{N}$ so that for all $n \geq m$,

$$\rho(T^n x, T^n y) \leq k \rho(x, y).$$

Then for $n \geq m$,

$$\rho(x, T^n y) \leq \rho(x, T^n x) + \rho(T^n x, T^n y) \leq r + k \rho(x, y).$$

This proves that $(T^n y)_{n \geq m} \subset B(x; d)$ where $d = r + k \rho(x, y)$. Let

$$d' = \max \{ \rho(x, T^i y) : i = 1, \dots, m - 1 \}.$$

Then $O(y) \subset B(x; d^*)$ where $d^* = \max \{ d, d' \}$. Since y is arbitrary, all orbits of T are bounded. \square

We now show that the answer to Question 1 is negative. The simplest complete \mathbb{R} -tree is a closed real line interval. For this case we recall a classical theorem due to Ralph DeMarr.

Theorem 3.7 (DeMarr [4]). *Let I be a closed real line interval, and let f and g be commuting continuous mappings of I into itself which have respective Lipschitz constants α and β satisfying the condition $\beta(\alpha - 1) < (\alpha + 1)$. Then f and g have at least one common fixed point.*

If we take $\alpha = \beta$ in DeMarr's condition we find that the condition $\beta(\alpha - 1) < (\alpha + 1)$ reduces to $\alpha < 1 + \sqrt{2}$. This leads to the following result which shows that in Theorem 2.4 the constant 2 is not always optimal. Notice that here we are not assuming T is continuous.

Theorem 3.8. *Let I be a closed real line interval and suppose $T : I \rightarrow I$ satisfies all $n \in \mathbb{N}$ sufficiently large,*

$$|T^n x - T^n y| \leq k_n |x - y|$$

for each $x, y \in I$. If $\limsup_{n \rightarrow \infty} k_n < 1 + \sqrt{2}$, then T has a fixed point.

Proof. Choose N so large that both T^N and T^{N+1} have Lipschitz constant less than $1 + \sqrt{2}$. Since T^N and T^{N+1} are continuous and commute, by DeMarr’s Theorem there exists $x_0 \in I$ such that $T^N x_0 = T^{N+1} x_0 = x_0$. This clearly implies $T x_0 = x_0$. □

Theorem 3.9. *Let (X, ρ) be a complete geodesically bounded \mathbb{R} -tree, and suppose $T : X \rightarrow X$ satisfies for all $n \in \mathbb{N}$ sufficiently large,*

$$\rho(T^n x, T^n y) \leq k_n \rho(x, y)$$

for each $x, y \in X$, where $\limsup_{n \rightarrow \infty} k_n < 2$. Then T has a fixed point.

Proof. For n sufficiently large, T^n is lipschitzian and hence has a fixed point by Theorem 3.1. Therefore T has a bounded orbit, so the conclusion follows from Theorem 2.4 and Proposition 3.6 □

Question 2. Can the assumption that X is geodesically bounded in Theorem 3.1 be replaced with the assumption that T has bounded orbits?

Question 3. Can the assumption that $\limsup_{n \rightarrow \infty} k_n < 2$ in Theorem 3.9 be replaced with the assumption that $\limsup_{n \rightarrow \infty} k_n < \infty$?

It is easy to see that if a continuous mapping $f : \mathbb{R} \rightarrow \mathbb{R}$ has a bounded orbit, then it has a fixed point. Suppose $\{f^n x\}$ is bounded. If this sequence is monotone, then clearly $\lim_{n \rightarrow \infty} f^n x$ is a fixed point of f . Otherwise there exists $n \in \mathbb{N}$ such that $f^n x \leq f^{n+1} x$ and $f^{n+2} x \leq f^{n+1} x$, in which case f has a fixed point in the interval $[f^n x, f^{n+1} x]$, or such that $f^{n+1} x \leq f^n x$ and $f^{n+1} x \leq f^{n+2} x$, in which case f has a fixed point in $[f^{n+1} x, f^n x]$.

Question 4. If T is a continuous mapping of a complete \mathbb{R} -tree X into itself, and if T has a bounded orbits, then does T have a fixed point?

Remark 3.10. The answer to Question 4 is ‘no’ if just a single orbit is assumed to be bounded even if that orbit is a periodic point. Let $X = [0, \infty) \cup [x, y]$ where $x = (0, -1)$ and $y = (0, 1)$. Let $u = (0, -\frac{1}{2})$ and $v = (0, \frac{1}{2})$, and let 0 denote the origin. Reflect x and y in the origin, stretch the intervals $[x, u]$ and $[y, v]$ so that u and v touch the origin, and shift the intervals $[u, 0]$ and $[v, 0]$ onto the x -axis pushing $[0, \infty)$ to the right. By moving u and v nearer to each other an example can be constructed for which the mapping is lipschitzian with Lipschitz constant arbitrarily near 1.

Theorem 2.4 applied to the case when X is the real line \mathbb{R} asserts that if $T : \mathbb{R} \rightarrow \mathbb{R}$ has bounded orbits and satisfies

$$|T^n x - T^n y| \leq k_n |x - y|$$

for each $x, y \in \mathbb{R}$, where $\limsup_{n \rightarrow \infty} k_n < 2$, then T has a fixed point. This raises the obvious question of whether 2 can be replaced with the estimate $1 + \sqrt{2}$ of Theorem 3.8. (Of course this result is of interest only for discontinuous mappings T , since it is easy to see that a continuous mapping of \mathbb{R} into \mathbb{R} with a bounded orbit always has a fixed point.)

Remark 3.11. Continuity of T was crucial to the *proof* of Theorem 3.2. However we do not know whether this assumption is essential.

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